Welcome to one of the most versatile pixel controller available. This controller supports the conversion of multi-cast E1.31 Ethernet to many pixel formats, Renard and DMX. Now you do not have to buy separate controller for AC control and pixels. The board also supports LED matrix panels, so it can be configured for many applications. The outputs on the board allow you to customize the outputs to meet your needs.
**SIXTEEN UNIVERSE CONTROLLER**

**SPECIFICATIONS:**
- Supports multi-cast Ethernet E1.31
- Supports 16/24 universes of 512 channels each, 170 pixels (RGB)
- Supports 8 matrix LED panels 16x32 (8 to 1 scan) 16M colors, 85 Hertz refresh
- High performance controller, no dropped packets, scan rates up to 5mS
- Supports gamma correction (matches colors on computer)
- Supports both 5V and 12V strings

Renard serial at 56.7K, 115.2K, 230.4K, 460.8K
DMX (Supports WS2822)
WS2801 and compatible
WS2811 and compatible
WS2812B
TM1804 (untested)
TM1803/TM1809 (untested)
TM1829 (untested)
Servo Output

An FPGA is a poor man’s custom digital chip. These chips are much better suited to controlling pixel’s, since they can easily manage many processes at the same time. The board is a simple two layer printed wiring board to connect the daughter cards to a standard 14-pin connector for output of the universes. The board has eight 14-pin connectors with 4 universes each. These output connectors allow universes to be added as required for your lighting application. Normally, the output connector will go to a buffer board which can support any type of output buffer and power as required for your application.

The best part of having an FPGA for the output of the pixels strings is that there are actually 16 output controllers that operate in parallel. So once the first byte of a message has arrived, the output machine is send the data to your pixels. The controller supports any number of channels for each output. So for the WS2801, that have a cycle time of 1.2 uS, the data is sent out in 1.2uS * 8 * 512 which equals about 5mS, which is a cycle time of 200 hertz. So you can update your pixels at a very fast rate.
**SIXTEEN UNIVERSE CONTROLLER**

The off the shelf FPGA module and Ethernet module allow this kit to be user friendly for the do it yourself user. The difficult to solder components are already soldered to the two daughter boards. So all you need to do is solder headers.

**SWITCHES & LEDS:**

The reset switch is the small pushbutton on the FPGA card. The switches and LED have the following functions:

- **RESET** - Universe test (all channels 1/4 brightness)

Revisions thru C
- LED1 (D6) - Lights when Ethernet traffic is available for controller.
- LED2 (D4) - Clock from Ethernet module good (Blinking at 5 hertz).
- LED3 (D2) - Alternate clock blinking (Blinking at 5 hertz).

Revision D
- LED1 (D6) - Always ON
- LED2 (D4) - Lights when Ethernet traffic is available for controller.
- LED3 (D2) - Clock from Ethernet module good (Blinking at 5 hertz).

**ETHERNET MODULE:**

The Ethernet module interfaces to the FPGA with RMII physical interface. The FPGA is designed to function only at 100Mbit/sec. Both the green and yellow LED should illuminate when the module is connected to the computer. If the yellow light does not lite, it indicates that the link is 10Mbit/sec. The green light will flash during Ethernet traffic. Note, that this controller does not support the IGMP messages. (Used thru revision C). Can be used on revision D using pins 1-14.
The LAN8720 is used on revision D of the circuit card due to lower cost. Since they are inexpensive it is reasonable to add a second board to allow for daisy chaining. The revision D board allows other controllers to be included in the Ethernet daisy chaining, since the communication is bi-direction. The other controllers would be placed at the end of the chain. The revision D board will only use data on the receive Ethernet port. The latency thru the controller in either direction is 700nS maximum. The maximum number of controllers to daisy chain is dependent upon the controlling computer and how many packets can be sent over 100Mbit Ethernet. For example, a full E131 packet requires 56uS to send. The maximum number of packets you can send in 25mS is approximately 400, which limits you to 16 controllers of 24 universes.

Daisy Chaining

With both revision A, B and D it is important to insure that there is enough spacing between the Ethernet board and the top of the motherboard. Revision B supports two methods of mounting, using a right angle or straight header as shown below.
My preference for revision B is to remove the right angle connector and install a straight connector. In either case the board is marked with the correct location to install the Ethernet board. This installation type is more rigid and does not require standoffs as shown in the picture below.

**INPUT POWER:**

The input power for revision A is +5.0Vdc through the terminal block. The input is routed through a diode to protect the FPGA daughter card from reverse input voltages. The power draw will be approximately 0.08 ampere for the FPGA and the Ethernet board, plus power for the buffer cards. The +5.0Vdc is routed directly to the universe headers. So there is no protection for the daughter cards.

Revision B can also be run off a 5Vdc input as shown in the figure below. The 5V header must either have a jumper installed or a wire.
Revision B and D also supports higher input power, where the voltage regulator and three capacitors (C1, C2, C3) are installed on the board along with the voltage regulator. The voltage regulator is rated from 7V to 36Vdc power input. With the voltage regulator installed, do not install the 5Vdc header, as shown in the picture below.

Revision B/D 5VDC header - J18

As shown in the 12Vdc power header picture, the jumper J20 will connect the Raspberry PI power to the controller board. This allows you to power the PI separately or through the controller.

Revision B/D 5VDC header - J20
The configuration of the outputs is accomplished through jumpers.

<table>
<thead>
<tr>
<th>Output type configuration.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Standard output headers (3.3Vdc CMOS)</td>
</tr>
<tr>
<td>Base multi-cast universe for reception of data.</td>
</tr>
</tbody>
</table>

Universal Output Header
The output connector for each universe is shown above. The pins are selected to allow the connector to be inserted backwards and still have the same power and ground connections. However, the universe outputs will not be correct. Two output pins are available for each of the universes.

<table>
<thead>
<tr>
<th>PINS</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1,14</td>
<td>5.0Vdc</td>
</tr>
<tr>
<td>4,5</td>
<td>Ground</td>
</tr>
<tr>
<td>10,11</td>
<td>Ground</td>
</tr>
<tr>
<td>2</td>
<td>Universe 1A (Data output)</td>
</tr>
<tr>
<td>3</td>
<td>Universe 1B (Clock output, if required)</td>
</tr>
<tr>
<td>6</td>
<td>Universe 2A</td>
</tr>
<tr>
<td>7</td>
<td>Universe 2B</td>
</tr>
<tr>
<td>8</td>
<td>Universe 3A</td>
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<tr>
<td>9</td>
<td>Universe 3B</td>
</tr>
<tr>
<td>12</td>
<td>Universe 4A</td>
</tr>
<tr>
<td>13</td>
<td>Universe 4B</td>
</tr>
</tbody>
</table>

**GAMMA CORRECTION:**

Gamma correction is selected by not installing jumper 16 for HEADER A. When the jumper is installed there is no gamma correction. This is a pullup resistor input to the FPGA, which may be changed with power on. Gamma correction was removed after version A, since this feature is available in most software.
LED’s:

LED’s D2 and D4 will alternate flash on the FPGA board when it is correctly programmed and the Ethernet module is installed. LED D6 will flash when data is within the multi-cast range of the board (revisions thru C).

For revision D of the controller, LED’s D6 will remain on. LED D2 will flash when the board is correctly programmed and the Ethernet module is installed. LED D4 will flash when data is within the multi-cast range of the board.

OUTPUT TYPE SELECTION:

The selection of the output type for each universe is selected with a ten pin header. This provides for 32 types of output pixels. The values are read at power up, so if you change the jumpers, re-apply power. A jumper selects a zero for that particular bit position. If an invalid type is selected the group of universes is set to off. Currently, the jumper on Bit 16 is ignored.

Header types 1-4 sets the output type on header universe 1-4.
Header types 5-8 sets the output type on header universes 5-8.
Header types 9-12 sets the output type on header universes 9-12.
Header types 13-16 sets the output type on header universes 13-16.

<table>
<thead>
<tr>
<th></th>
<th>0000</th>
<th>0001</th>
<th>0010</th>
<th>0011</th>
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</thead>
<tbody>
<tr>
<td>1</td>
<td>Renard (57.6K): The output header is always 0x7E, 0x80 hex. These values are followed by up to 512 bytes. The special two byte character values for 0x7D, 0x7E, and 0x7F are supported.</td>
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<td>16</td>
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<tr>
<td></td>
<td>Renard (115.2K)</td>
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<td>16</td>
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<td></td>
<td>Renard (230.4K)</td>
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<td>16</td>
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<tr>
<td></td>
<td>Renard (460.8K)</td>
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<tr>
<td>Code</td>
<td>Description</td>
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<td>-----------------------------------------------------------------------------------------------------------------------------------------------</td>
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<tr>
<td>0100</td>
<td>DMX: The start byte in the E1.31 is ignored and a 0x00 is always used. The break is 92-96uS, followed by a 12uS NAB. Once the bytes are transmitted, the output remains in idle till the next packet.</td>
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<tr>
<td>0101</td>
<td>WS2801: The output clock is 781.25KHz, with the data changing on the falling edge. The low data rate is to maintain the data rate similar to other types of output pixels, which are generally around 800KHz. Between each of the bytes there is a half clock delay.</td>
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<td></td>
<td>Not used - output off</td>
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<td></td>
<td></td>
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<tr>
<td></td>
<td>Not used 0 output off</td>
<td></td>
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<tr>
<td>1000</td>
<td>WS2811 - The output timing is based on a 12.5MHz clock. The zero output times are 0.24/0.96 uS and the one output times are 0.56/0.64 uS. Once the message is sent the output will stay in a low state to load the values.</td>
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<tr>
<td>1001</td>
<td>WS2812B - PREFERRED TIMING FOR WS28XX pixels. The output timing is based on a 12.5MHz clock. The zero output times are 0.40/0.80 uS and the one output times are 0.80/0.48 uS. Once the message is sent the output will stay in a low state to load the values.</td>
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<tr>
<td>1010</td>
<td>TM1804 (untested) - The output timing is based on a 12.5MHz clock. The zero output times are 0.48/0.96 uS and the one output times are 0.96/0.48 uS. Once the message is sent the output will stay in a low state to load the values.</td>
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<tr>
<td>1011</td>
<td>TM1803 &amp; TM1809 (untested) - The output timing is based on a 12.5MHz clock. The zero output times are 0.32/0.64 uS and the one output times are 0.64/0.32 uS. Once the message is sent the output will stay in a low state to load the values.</td>
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</tbody>
</table>
### 1100  TM1829 (untested) - The output timing is based on a 12.5MHz clock. The zero output times are 0.32/0.88 uS and the one output times are 0.80/0.40 uS. Once the message is sent the output will stay in a high state to load the values.

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</table>

Not used - turns output off

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<th>1</th>
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Servo Output - only on outputs 9-16 (for a total of 16 outputs)
See write up on servo outputs

<table>
<thead>
<tr>
<th>1</th>
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</table>

1111  On universes 1-4 this places Renard 56.7K baud outputs 1/2 and DMX on outputs 3/4.
   On universes 5-8 this places Renard 115.2K baud outputs 5/6 and DMX on outputs 7/8.
   On universes 9-12 this places Renard 230.4K baud outputs 7/8 and DMX on outputs 11/12.
   On universes 13-16 this places Renard 460.8K baud outputs 13/14 and DMX on outputs 15/16.

<table>
<thead>
<tr>
<th>1</th>
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<th>8</th>
<th>16</th>
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</table>

**SERVO OUTPUTS:**
The servo output mode is only available on outputs 9 thru 16. Each output channel uses both clock and data for servo output, where data is servo output 1 and clock is servo output 2. The servo output supports servo outputs at 50 hertz, where the pulse width can varying from 0.012mS to 3.072mS. The output pulse width for servo 1 is determined by the first three channels 0,1,2; and servo output pulse width is determined by channels 3,4,5. The output pulse width is 12uS + sum of channels(0,1,2)*4uS

For example:
channel 0,1,2 all zero equals output timing of 12uS for servo output 1.
channel 0 =255, channel 1,2 = 0 equals output timing of 12uS+4uS*255 = 1.032mS for servo output 1
channel 0,1=255, channel 2 = 0 equals output timing of 12uS+4uS*510 = 2.052mS for servo output 1
channel 0,1,2 = 255 equals output timing of 12uS+4uS*765 = 3.072mS for servo output 1
channel 3,4,5 = 255 equals output timing of 12uS+4uS*765 = 3.072mS for servo output 2
OUTPUT TYPE SELECTION:
There is one connector to select the base universe address. The connector has five pins and the jumpers inserted selects a zero for the bit position. The base universe address for board is sixteen. This is shown below:

With all of the jumpers installed this selects a base universe of 16.

Thru revision C
00000 - 16-31  01000 - 128-143  10000 - 256-271  11000 - 384-399
00001 - 16-31  01001 - 144-1591  10001 - 272-287  11001 - 400-415
00011 - 48-63  01011 - 176-191  10011 - 304-319  11011 - 432-447
00100 - 64-79  01100 - 192-207  10100 - 320-335  11100 - 448-463
00101 - 80-95  01101 - 208-223  10101 - 336-351  11101 - 464-479
00110 - 96-111 01110 - 224-239  10110 - 352-367  11110 - 480-495
00111 - 112-127 01111 - 240-255  10111 - 368-383  11111 - 496-511

The output mapping for a base of 16:

Output 1 - universe 16
Output 2 - universe 17
Output 3 - universe 18
...
Output 15 - universe 30
Output 16 - universe 31

Revision D
00000 - 32-63  01000 - 255-287  10000 - 512-543  11000 - 768-799
00001 - 32-63  01001 - 288-319  10001 - 544-575  11001 - 800-831
00010 - 64-95  01010 - 320-351  10010 - 576-607  11010 - 832-863
00100 - 128-159 01100 - 384-415  10100 - 640-671  11100 - 896-927
00101 - 160-191 01101 - 416-447  10101 - 672-703  11101 - 928-959
00110 - 192-223 01110 - 448-479  10110 - 704-735  11110 - 960-991
00111 - 224-255 01111 - 480-511  10111 - 736-767  11111 - 992-1023

The first eight outputs for revision D now support 2 universes of pixels or 341 full color LED lights. The data should be continuous from universe 1 to universe 2, where in universe 1 the 512 channel is used.

The output mapping for a base of 32:
SIXTEEN UNIVERSE CONTROLLER

Output 1 - universe 32, 33
Output 2 - universe 34, 35
Output 3 - universe 36, 37
Output 4 - universe 38, 39
Output 5 - universe 40, 41
Output 6 - universe 42, 43
Output 7 - universe 44, 45
Output 8 - universe 46, 47

Output 9 - universe 48
Output 10 - universe 49
Output 11 - universe 50
Output 12 - universe 51
Output 13 - universe 52
Output 14 - universe 53
Output 15 - universe 54
Output 16 - universe 55

Universe 56 thru 63 at not used.

5Vdc Buffer Board
SIXTEEN UNIVERSE CONTROLLER

The 5Vdc buffer board is compatible with any two of the universe outputs. The sixteen universe board supports two of these boards. This particular board only supports three channel pixels, so there is no clock output. The driver for the board is a 74ACT541 part, that has higher current than the normal driver to support driving pixels further. The output source termination resistor is 120 ohms, which is chosen to match the impedance of a twisted pair cable (normally 100-120 ohms). Since Ethernet cable is inexpensive, it is recommend to use this for all outputs. The U1-U8 should be on one signal on the pair and the second wire should be connected to ground. Using Ethernet cable, these outputs have driven 50 WS2811 pixels at a 100 feet. Please test your own wiring to ensure that it work for your particular application.

If you are driving 5V pixels, this setup will provide an excellent performance with 33 ohm source termination on the board and 680/170 ohm termination on the receiving end. 170 to +5Vdc and input signal, and 680 to input signal and ground.

All pixels are driven with 5Vdc logic, except for the TLS3XXX series (3.3Vdc inputs). So power the pixels normally from 5V or 12V power. The U1 to U8 outputs correspond to universe outputs 1-8. The ground is shared between the outputs to reduce the connector size.

100 Feet With Only Source Termination
100 Feet with 33 Ohm Source Termination and 170/680 Termination
The quad buffer board is shown below. It supports the output of four universes in either Renard or DMX format. The output buffers are bandwidth limited to 2MHz to limit the noise in your system and to increase maximum cable length. This will help reduce any interference to your FM broadcast. These buffers were tested to cable lengths of 200 feet.

If you are using a three wire pixel format such as serial, DMX, WS2811, the output buffer board can support putting two universes on one cable. When the jumpers on in the four position all connectors are active, if the jumpers are in the two position connectors 1 and 3 are active with two universes each.

The pin out for the Renard on Ethernet cable is shown below:
1 - Ground
2 - Ground
3 - No connect
4 - Output negative (-)
5 - Output positive (+)
6 - No connect
7 - No connect
8 - No connect

The pin out for the DMX on Ethernet cable is shown below:
1 - Data out positive (+) or universe 1
2 - Data out negative (-) or universe 1
3 - Clock out positive (+) or universe 2
4 - No connect
5 - No connect
6 - Clock out negative (-) or universe 2
7 - Ground
8 - Ground
DMX Receiver Board

The DMX receiver board can be used with either 5V or 12V pixels. There is an internal regulator that will support either voltage type. The board can either be powered through the power connector or through the power from the pixel string. The receiver supports two channels of RS-485, which can either be a four wire pixel string or two universes of output.
Example Wiring

Wiring of RX to Single String
RX Receiver, Wiring for Powering From Center of Strip
SIXTEEN UNIVERSE CONTROLLER

RX Receiver, Multiple String Wiring and Power
Example Wiring 5V Buffer
Revisions

Revision - : Baseline
Revision A : Added gamma correction.
Revision B: Added information for revision B board
Revision C: Added information about LED’s and to use WS2812 pixel as the standard output.
Revision D: Added information output 2 universe support for first 8 outputs.
Revision E: Added information for servo outputs.